# Six-Field Model and RELAP5-3D

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- Six Field Equations
- Data to match
- Solution Algorithm
- RELAP Model
- Changes to Code
- Results
- References

#### Motivation for Six-Field Model

#### • Two-field models

- Limited capability to model reactor transients and accidents
- Cannot capture differences in temperature between liquid and droplet fields
- Cannot track location of droplets or bubbles
- Six-field models
  - Improved accuracy of the calculations
  - Better accuracy will improve efficiency of nuclear reactor systems

#### Six Field Nomenclature

Index	Description
1	Continuous Liquid
2	Large Droplet
3	Small Droplet
4	Continuous Vapor
5	Large Bubble
6	Small Bubble

- Subscripts on terms in governing equations will indicate which field relates to that term
- Terms that refer to transition between fields (e.g., droplet entrainment, large droplets breaking into small droplets), two subscripts are provided.
  - The first subscript is the source field
  - The second subscript will indicate the result field (e.g. S<sub>2,3</sub>).

## **Droplet Field Entrainment in RELAP5-3D**

- First step in six-field implementation
- Single droplet field (small droplets) modeled
- Graded approach allows for confirmatory calculations before proceeding
- Entrainment correlation is added to vexplt
  - Computes rate of droplet entrainment based on local conditions in each control volume
  - Droplets not convected to other volumes
  - Droplets "disappear" each timestep

## MASS (Continuity) Balance Governing Equations

- Continuous Liquid
- $\frac{\partial}{\partial t}(\alpha_1 \rho_f) + \nabla \cdot (\alpha_1 \rho_f \vec{v}_1) = -\Gamma_1 Sink + Source$
- Droplet Field

• 
$$\frac{\partial}{\partial t}(\alpha_3\rho_f) + \nabla \cdot (\alpha_3\rho_f\vec{v}_3) = -\Gamma_3 - Sink + Source$$

• Continuous Vapor

• 
$$\frac{\partial}{\partial t}(\alpha_4\rho_g) + \nabla \cdot (\alpha_4\rho_g\vec{v}_4) = -\Gamma_4 - Sink + Source$$

# **MOMENTUM Governing Equations**

- Continuous liquid field
- $\alpha_1 \rho_f \frac{D\vec{v}_1}{Dt} = -\alpha_1 \nabla p_f + \alpha_1 \rho_f \vec{g}_1 + (\vec{v}_{i,1} \vec{v}_1)\Gamma_1 + M_{i,1} + M_{w,1} Sink + Source$
- Droplet field
- $\alpha_3 \rho_f \frac{D\vec{v}_3}{Dt} = -\alpha_3 \nabla p_f + \alpha_3 \rho_1 \vec{g}_3 + (\vec{v}_{i,3} \vec{v}_3)\Gamma_3 + M_{i,3} Sink + Source$
- Continuous vapor field

• 
$$\alpha_4 \rho_g \frac{D\vec{v}_4}{Dt} = -\alpha_4 \nabla p_g + \alpha_4 \rho_g \vec{g}_4 + (\vec{v}_{i,4} - \vec{v}_4)\Gamma_4 + (\vec{v}_{i,3} - \vec{v}_4)\Gamma_3 + M_{i,4} + M_{w,4} - Sink + Source$$

Where:

 $\vec{g}$  – Body force (i.e., gravity)

 $\vec{v}$  – Velocity of the field (subscript *i* indicates near the interface)

M<sub>i,1</sub> – Momentum source from interfacial drag between continuous liquid and continuous vapor

 $M_{\text{w,1}}-Momentum$  source from interfacial drag between continuous liquid and the wall

# **ENERGY Governing Equations**

- Continuous liquid
- $\alpha_1 \rho_f \frac{Dh_1}{Dt} = \alpha_1 \frac{Dp_f}{Dt} + \Phi_1^T + \Phi_1^\mu + \Gamma_{i,1}(h_{i,1} h_1) + \Gamma_{w,1}(h_{w,1} h_1) + a_i q_{i,1}^{\prime\prime\prime} + a_{w,1} q_{w,1}^{\prime\prime\prime\prime} + M_{i,1}(\vec{v}_{i,1} + \vec{v}_1) Sink + Source$
- Droplet field
- $\alpha_3 \rho_f \frac{Dh_3}{Dt} = \Gamma_{i,3} (h_{i,3} h_3) + a_i q_{i,3}^{\prime\prime\prime} + M_{i,3} (\vec{v}_{i,3} + \vec{v}_3) Sink + Source$
- Continuous vapor

• 
$$\alpha_4 \rho_g \frac{Dh_4}{Dt} = \alpha_4 \frac{Dp_g}{Dt} + \Phi_4^T + \Phi_4^\mu + \Gamma_{i,4}(h_{i,4} - h_4) + \Gamma_{w,4}(h_{w,4} - h_4) + \Gamma_{i,3-4}(h_{4,3} - h_4) + a_i q_{i,4}^{\prime\prime\prime} + a_{4,3} q_{4,3}^{\prime\prime\prime} + a_{w,4} q_{w,4}^{\prime\prime\prime} + M_{i,4}(\vec{v}_{i,4} + \vec{v}_4) - Sink + Source$$

Where:

 $\Phi$  – Viscous dissipation (superscript m) or turbulent work effect (superscript T)

*h* – Enthalpy (subscript *i* indicates interface)

*a* – interfacial area concentration (area per unit volume) at the *w*-wall or *i*-interface

 $q^{\prime\prime\prime}$  – Heat flow to continuous liquid from the *w*-wall or *i*-interface to the field

#### **Droplet Entrainment**

- Three primary entrainment mechanisms
  - Reflood droplets entrained by flashing vapor
  - Vertical annular flows droplets entrained from wave formation
  - Horizontal annular flows droplets entrained from wave formation
- Annular wave entrainment
  - Wavelets form on annular flow surface from shear with vapor flow
  - Tops of wavelets pulled by shear forces
  - Sufficient shear overcomes surface tension, and droplets are entrained





- Source of mass to droplet field
- Sink of mass from the continuous liquid field
- Droplet entrainment model

• 
$$S_{1,3}^{\prime\prime\prime} = \frac{k_A^{\prime} U_g^2 (\rho_g \rho_f)^{1/2} (W_{film} - W_{LFC})}{p \sigma t_{film}}$$

## **Entrainment Model Implementation in RELAP5-3D**

- Two data structures added
  - Contain droplet-specific values for junctions and volumes
- Immediately prior to call to vexplt in the hydro module, droplet specific values are updated with liquid field parameters
  - Limits entrainment results to a single timestep



- Simple case that allows for 2-phase flow with control of the vapor and liquid velocities
- Two-volume PIPE connected to source and sink TDVs
- Inlet controlled by TDJ, outlet is a single junction



# **Test Case Conditions**

- Inlet conditions
  - T = 422.0 K
  - X = 0.9
  - Mflowg = 0.1 kg/s -> 0.5 kg/s
  - Mflowf = 10 kg/s
- Test section PIPE
  - FA = 1.0 m<sup>2</sup>
  - L = 2.0 m (each volume)
  - V = 2.0 m<sup>3</sup> (each volume)

#### **Test Section Vapor Flows**



#### **Droplet Entrainment Rate**

- Volume of each PIPE cell is 2 m<sup>3</sup>
- Liquid fractions as high as 0.0003
- Droplet entrainment peaks at ~4 kg/m<sup>3</sup>-s
- Approximately 0.0024 kg of droplets entrained every second





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